Contents lists available at Science-Gate



International Journal of Advanced and Applied Sciences

2

Journal homepage: http://www.science-gate.com/IJAAS.html

On some new i-convergent double sequence spaces defined by a compact operator



CrossMark

Vakeel A. Khan¹, Hira Fatima¹, Ayhan Esi^{2,*}, Sameera A.A. Abdullah¹, Kamal M.A.S. Alshlool¹

¹Department of Mathematics, Aligarh Muslim University, Aligarh 202002, India ²Department of Mathematics, Adiyaman University, Adiyaman, Turkey

ARTICLE INFO

Article history: Received 29 December 2016 Received in revised form 29 February 2017 Accepted 3 March 2017 Keywords: Compact operator Orlicz function I- convergence

ABSTRACT

In this article we introduce and study some I-convergent double sequence spaces ${}_{2}S'(M)$, ${}_{2}S0'(M)$, ${}_{2}S\infty'(M)$ with the help of compact operator T on the real space \mathbb{R} and an Orlicz function M. We study some of its topological and algebraic properties and prove some inclusion relations on these spaces.

© 2017 The Authors. Published by IASE. This is an open access article under the CC BY-NC-ND license (http://creativecommons.org/licenses/by-nc-nd/4.0/).

1. Introduction

Let $\mathbb{N}, \mathbb{R}, \mathbb{C}$ be the sets of all natural, real, and complex numbers respectively. We denote

$$_{2}\omega = \{x = (x_{ii}) \colon x_{ii} \in \mathbb{R} \text{ or } \mathbb{C}\}$$

$$(1.1)$$

showing the space of all real or complex double sequences.

Definition 1.1: Let X and Y be two normed linear spaces. An operator $T: X \rightarrow Y$ is said to be a compact linear operator (or completely continuous linear operator), if :(i) T is linear. (ii) T maps every bounded sequence (x_k) in X onto a sequence $T(x_k)$ in Y which has a convergent subsequence.

The set of all compact linear operators C(X, Y) is a closed subspace of $\mathcal{B}(X, Y)$ and C(X, Y) is a Banach space if Y is a Banach space. Throughout the paper, we denote $2l_{\infty}$, 2c and $2c_0$ as the Banach spaces of bounded, convergent, and null double sequences of reals respectively with the norm:

$$\|x\| = \sup_{i,j\in\mathbb{N}} x_{ij}.$$
 (1.2)

Following Başar and Altay (2003) and Sengonul (2007), we introduce the double sequence spaces $_{2S}$ and $_{2S_0}$ with the help of compact operator T on \mathbb{R} as follows:

* Corresponding Author.

Email Address: aesi23@hotmail.com (A. Esi)

This is an open access article under the CC BY-NC-ND license (http://creativecommons.org/licenses/by-nc-nd/4.0/)

$$S = \{x = (x_{ij}) \in {}_{2}l_{\infty}, T(x) \in {}_{2}c\}$$

$$S_{0} = \{x = (x_{ij}) \in {}_{2}l_{\infty}, T(x) \in {}_{2}c_{0}\}.$$

As a generalization of usual convergence, the concept of statistical convergent was first introduced by Fast (1951) and also independently by Buck (1953) and Schoenberg (1959) for real and complex sequences. Later on, it was further investigated from a sequence space point of view and linked with the Summability theory by Šalát (1980) and Tripathy (2004).

Definition 1.2: A double sequence $x = (x_{ij}) \in {}_2\omega$ is said to be I-convergent to a number L if for every $\epsilon > 0$, we have

$$\{(i,j) \in \mathbb{N} \times \mathbb{N} : |x_{ij} - L| \ge \epsilon\} \in I.$$
(1.3)

In this case, we written $I - \lim_{ij} (x_{ij}) = L$. The notation of ideal convergence (I-convergence) was introduced and studied by Kostyrko et al. (2000, 2005). Later on, it was studied by Šalát et al. (2004, 2005), Tripathy and Hazarika (2009, 2011), Khan and Ebadullah (2011, 2012, and 2013). Now, we recall the following definitions:

Definition 1.3: Let X be a non-empty set. Then, a family of sets $I \subseteq 2^X$ is said to be an Ideal in X if

1. $\varphi \in I$;

- 2. I is additive; that is, $A, B \in I \Rightarrow A \cup B I \in I$; 2. Lie have different that is, $A \in I \cap D$.
- 3. I is hereditary that is, $A \in I, B \subseteq A \Rightarrow B \in I$.

An Ideal $I \subseteq 2^x$ is called non trivial if $I \neq 2^x$. A non-trivial ideal $I \subseteq 2^x$ is called admissible if $\{\{x\}: x \in X\} \subseteq I$.

https://doi.org/10.21833/ijaas.2017.04.007

²³¹³⁻⁶²⁶X/© 2017 The Authors. Published by IASE.

A non-trivial ideal I is maximal if there cannot exist any non-trivial ideal $J \neq I$ containing I as a subset.

Definition 1.4: A non-empty family of sets $\mathcal{F} \subseteq 2^{X}$ is said to be filter on X if and only if

1. $\emptyset \notin \mathcal{F}$; 2. For, A, B $\in \mathcal{F}$ we have $A \cap B \in \mathcal{F}$; 3. For each $A \in \mathcal{F}$ and $A \subseteq B$ implies $B \in \mathcal{F}$.

For each ideal I, there is a filter $\mathcal{F}(I)$ corresponding to I. That is,

$$\mathcal{F}(I) = \{K \subseteq N : K^c \in I\}, \text{ where } K^c = N - K. \quad (1.4)$$

Definition 1.5: A double sequence $(x_{ij}) \in {}_2\omega$ is said to be I - null if L = 0. In this case, we write

$$I - \lim x_{ij} = 0.$$
 (1.5)

Definition 1.6: A double sequence $(x_{ij}) \in {}_2\omega$ is said to be I-Cauchy if for every $\epsilon > 0$ there exists numbers $m = m(\epsilon), n = n(\epsilon)$ such that

$$\{(i,j) \in \mathbb{N} \times \mathbb{N} : |x_{ij} - x_{mn}| \ge \epsilon\} \in I.$$
(1.6)

Definition 1.7: A double sequence $(x_{ij}) \in {}_2\omega$ is said to be I-bounded if there exists M > 0 such that

$$\{(i,j) \in \mathbb{N} \times \mathbb{N} : |x_{ij}| > M\} \in I.$$

$$(1.7)$$

Definition 1.8: A double sequence space E is said to be solid or normal if $(x_{ij}) \in E$ implies that $(\alpha_{ij}x_{ij}) \in E$ for all sequence of scalars (α_{ij}) with $|\alpha_{ij}| < 1$ for all $(i, j) \in \mathbb{N} \times \mathbb{N}$.

Definition 1.9 A double sequence space E is said to be symmetric if $(x_{\pi(i,j)}) \in E$ whenever $(x_{ij}) \in E$, where $\pi(i, j)$ is a permutation on \mathbb{N} .

Definition 1.10: A double sequence space E is said to be sequence algebra if $(x_{ij}, y_{ij}) \in E$ whenever $(x_{ij}), (y_{ij}) \in E$.

Definition 1.11: A double sequence space E is said to be convergence free if $(y_{ij}) \in E$ whenever $(x_{ij}) \in E$ and $x_{ij} = 0$ implies $y_{ij} = 0$, for all $(i, j) \in \mathbb{N} \times \mathbb{N}$.

Definition 1.12: Let $K = \{(n_i, k_j) : i, j \in N; n_1 < n_2 < n_3 < \dots$ and $k_1 < k_2 < k_3 < \dots\} \subseteq \mathbb{N} \times \mathbb{N}$ and E be a double sequence space. A K-step space of E is a sequence spaces:

$$\lambda_{\kappa}^{E} = \{(\alpha_{ij} x_{ij}) : (x_{ij}) \in E\}.$$

Definition 1.13: A cannonical preimage of a sequence $(x_{nikj}) \in E$ is a sequence $(b_{nk}) \in E$ defined as follows:

$$b_{n,k=} \begin{cases} x_{n,k} & \text{for } n, k \in K \\ 0, & \text{otherwise} \end{cases}$$

Definition 1.14: A sequence space E is said to be monotone if it contains the cannonical preimages of all its step spaces.

Definition.1.15: A function $M : [0, \infty) \rightarrow [0, \infty)$ is said to be an Orlicz function if it satisfies the following conditions;

1. M is continuous, convex and non-decreasing, 2. M (0) = 0, M(x) > 0 and $M(x) \rightarrow \infty$ as $x \rightarrow \infty$.

Remark: (i) If the convexity of an Orlicz function is replaced by $M(x + y) \le M(x) + M(y)$, then this function is called Modulus function (Tripathy and Hazarika, 2011).

(ii) If M is an Orlicz function, then $M(\lambda X) \leq \lambda M(x)$ for all λ with $0 < \lambda < 1$ (Tripathy and Hazarika, 2011). An Orlicz function M is said to satisfy $\Delta 2$ -condition for all values of u if there exists constant K > 0 such that $M(Lu) \leq KLM(u)$ for all values of L > 1 (Tripathy and Hazarika, 2011).

Lindenstrauss and Tzafriri (1971) used the idea of an Orlicz function to construct the sequence space

$$l_{M} = \left\{ x \in \omega, \sum_{k=1}^{\infty} M\left(\frac{x_{k}}{\rho}\right) < \infty \text{ for some } \rho > 0. \right\} (1.8)$$

The space l_{∞} becomes a Banach space with the norm

$$\|x\| = \inf \{\rho > 0, \sum_{k=1}^{\infty} M\left(\frac{|x_k|}{\rho}\right) \le 1\},$$
 (1.9)

which is called an Orlicz sequence space. The space l_M is closely related to the space l_p which is an Orlicz sequence space with $M(t) = t^p$ for $1 \le p < \infty$.

Later on, some Orlicz sequence spaces were investigated by Hazarika and Esi (2013), Maddox (1970), Parashar and Choudhary (1994), Bhardwaj and Singh (2000), Et (2001), Khan et al. (2016) Tripathy and Hazarika (2011), and many others.

Initially, as a generalization of statistical convergence, the notation of I-convergence was introduced and studied by Kostyrko et al. (2000). Later on, it was studied by Khan and Ebadullah (2013), Hazarika and Esi (2013), Šalát et al. (2004, 2005) and many others. We used the following lemmas for establishing some results of this article.

Lemma 1.1: Every solid space is monotone (Tripathy and Hazarika, 2011).

Lemma 1.2: Let F (*I*) and $M \subseteq N$. If $M \notin I$, then $M \cap K \notin I$.

Lemma 1.3: If $I \subseteq 2^N$ and $M \subseteq N$. If $M \notin I$, then $M \cap N \notin I$.

2. Main results

In this article, we introduce the following double sequence spaces:

$${}_{2}S^{I}(M) = \left\{ x = (x_{ij}) \in {}_{2}\omega: I - \lim M\left(\frac{|T(x_{ij}) - L|}{\rho}\right) = 0, \text{ for some } L \in \mathbb{C}, \rho > 0 \right\},$$

$$(2.1)$$

$${}_{2}S_{0}^{I}(M) = \left\{ x = \left(x_{ij} \right) \in {}_{2}\omega: I - \lim M\left(\frac{|T(x_{ij})|}{\rho} \right) = 0, \rho > 0 \right\},$$

$$(2.2)$$

$${}_{2}S_{\omega}^{I}(M) = \left\{ x = (x_{ij}) \in {}_{2}\omega: \exists K > Os. t. \left\{ i, j \in \mathbb{N}: M\left(\frac{|T(x_{ij})|}{\rho}\right) \ge K, \rho > 0 \right\} \in I \right\}$$

$$(2.3)$$

$${}_{2}S_{\infty}(M) = \left\{ x = (x_{ij}) \in {}_{2}\omega: \sup_{ij} M\left(\frac{|T(x_{ij})|}{\rho}\right) < \infty, \rho > 0 \in I \right\}$$
(2.4)

We also denote

 $2M_{\infty}^{I}(M) = 2S^{I}(M) \cap 2S_{\infty}(M)$ and $2M_{S_{0}}^{I}(M) = 2S_{0}^{I}(M) \cap 2S_{\infty}(M)$.

Theorem 2.1: For any Orlicz function M, the classes of double sequence

$${}_{2}S_{0}^{I}(M), {}_{2}S^{I}(M), {}_{2}M_{S_{0}}^{I}(M)$$
 and ${}_{2}M_{\infty}^{I}(M)$

are linear spaces.

Proof: Let $x = (x_{ij}), (\mathcal{Y}_{ij}) \in {}_{2}S^{l}(M)$ be any two arbitrary elements and let α, β be scalars. Now, since $x = (x_{ij}), (y_{ij}) \in {}_{2}S^{l}(M) \Rightarrow \exists$ some positive numbers $L_{l}, L_{2} \in \mathbb{C}$ and $\rho_{1}, \rho_{2} > 0$. Such that

$$I - \lim_{ij} M\left(\frac{|T(x_{ij}) - L_1|}{\rho_1}\right) = 0,$$
(2.5)

and

$$I - \lim_{ij} M\left(\frac{|T(\mathcal{Y}_{ij}) - L_2|}{\rho_2}\right) = 0.$$
(2.6)

For any $\epsilon > o$, the sets

$$A_{1} = \left\{ (i,j) \in \mathbb{N} \times \mathbb{N} \colon M\left(\frac{|T(x_{ij}) - L_{1}|}{\rho_{1}}\right) \ge \frac{\epsilon}{2} \in I \right\}$$
(2.7) and

$$A_2 = \left\{ (i,j) \in \mathbb{N} \times \mathbb{N} \colon M\left(\frac{|T(y_{ij}) - L_2|}{\rho_2}\right) \ge \frac{\epsilon}{2} \in I \right\}.$$
(2.8)

Let $\rho_3 = max\{2|\alpha|\rho_1, 2|\beta|\rho_2\}$. Since M is nondecreasing and convex function, we have

$$M\left(\frac{|T(\alpha x_{ij}+\beta Y_{ij})-(\alpha L_1+\beta L_2)|}{\rho_3}\right) = M\left(\frac{|\alpha T(x_{ij})+\beta T(Y_{ij})-\alpha L_1-\beta L_2|}{\rho_3}\right) \le M\left(\frac{|\alpha ||T(x_{ij})-L_1|}{\rho_3}\right) + M\left(\frac{|\beta ||T(Y_{ij})-L_2|}{\rho_3}\right) < M\left(\frac{|T(x_{ij})-L_1|}{\rho_1}\right) + M\left(\frac{|T(Y_{ij})-L_2|}{\rho_2}\right)$$
(2.9)

therefore, from (2.7), (2.8) and (2.9), we have

$$\begin{cases} (i,j) \in \mathbb{N} \times \mathbb{N} : M\left(\frac{|T(\alpha x_{ij} + \beta \mathcal{Y}_{ij}) - (\alpha L_1 + \beta L_2)|}{\rho_3}\right) \geq \epsilon, \\ (A_1 \cup A_2) \in I \end{cases} \subset$$

this implies that

$$\begin{cases} (i,j) \in \mathbb{N} \times \mathbb{N} : M\left(\frac{|T(\alpha x_{ij} + \beta \mathcal{Y}_{ij}) - (\alpha L_1 + \beta L_2)|}{\rho_3}\right) \ge \epsilon, \\ \in I \\ \Rightarrow \lim_{ij} M\left(\frac{|T(\alpha x_{ij} + \beta \mathcal{Y}_{ij}) - (\alpha L_1 + \beta L_2)|}{\rho_3}\right) = 0 \\ \Rightarrow \alpha x_{ij} + \beta y_{ij} \in 2S^I(M) \\ \Rightarrow 2S^I(M) \text{ is linear space and the proof of others follow similarly.} \end{cases}$$

Remark: For an Orlicz function M, the spaces ${}^{2}M^{I}_{s_{0}}(M)$, and ${}^{2}M^{I}_{s}(M)$ are Banach space normed by

$$\|x\| = \inf \left\{ \rho > o : \sup_{ij} M\left(\frac{|T(x_{ij})|}{\rho}\right) < 1, \rho > 0 \right\}.$$

Theorem 2.2: Let M_1 ; M_2 be two Orlicz functions and satisfying Δ_2 condition, then

a) $X(M_2) \subseteq X(M_1M_2)$ b) $X(M_1) \cap X(M_2) \subseteq X(M_1 + M_2)$ for $X = 2S^l, 2S_0^l, 2M_s^l$ (M) and $2M_{S_0}^l$

Proof: a) Let $x = (x_{ij}) \in {}_{0}S_{0}^{I}(M_{2})$ be an arbitrary element. *There exists* $\rho > 0$ *s.t*

$$I - \lim_{ij} M_2\left(\frac{|T(x_{ij})|}{\rho}\right) = 0.$$
 (2.10)

Let $\epsilon > 0$ and choose $0 < \delta < 1$ such that $M_1(t) < \epsilon$ for $0 \le t \le \delta$. Put $\mathcal{Y}_{ij} = M_2\left(\frac{|T(x_{ij})|}{\rho}\right)$ and consider,

$$\lim_{ij} M_1(\mathcal{Y}_{ij}) = \lim_{\mathcal{Y}_{ij} \le \delta, i, j \in \mathbb{N}} M_1(\mathcal{Y}_{ij}) + \lim_{\mathcal{Y}_{ij} > \delta, i, j \in \mathbb{N}} M_1(\mathcal{Y}_{ij}).$$
(2.11)

Now, since M_1 is an Orlicz function so we have $M_1(\lambda x) \le \lambda M_1(x), 0 < \lambda < 1$. Therefore we have,

$$\lim_{\mathcal{Y}_{ij} \le \delta, i, j \in \mathbb{N}} M_1(\mathcal{Y}_{ij}) \le M_1(2) \lim_{\mathcal{Y}_{ij} \le \delta, i, j \in \mathbb{N}} M_1(\mathcal{Y}_{ij})$$
(2.12)

for $\mathcal{Y}_{ij} > \delta$, we have $\mathcal{Y}_{ij} < \frac{\mathcal{Y}_{ij}}{\delta} < 1 + \frac{\mathcal{Y}_{ij}}{\delta}$. Now, since M_1 is non-decreasing and convex, it follows that,

$$M_1(\mathcal{Y}_{ij}) < M_1(1 + \frac{\mathcal{Y}_{ij}}{\delta}) < \frac{1}{2}M_1(2) + \frac{1}{2}M_1(\frac{2\mathcal{Y}_{ij}}{\delta}).$$
(2.13)

Since M_1 satisfies the Δ_2 - condition we have,

$$M_{1}(\mathcal{Y}_{ij}) < \frac{1}{2}K(\frac{y_{ij}}{\delta})M_{1}(2) + \frac{1}{2}KM_{1}(\frac{2y_{ij}}{\delta}) < \frac{1}{2}K\frac{y_{ij}}{\delta}M_{1}(2) + \frac{1}{2}K\frac{y_{ij}}{\delta}M_{1}(2) = K\frac{y_{ij}}{\delta}M_{1}(2).$$
(2.14)

This implies that,

$$M_1(\mathcal{Y}_{ij}) < K(\frac{\mathcal{Y}_{ij}}{\delta})M_1(2)$$
 (2.15)

hence, we have

$$\lim_{\substack{y_{ij}>\delta, i, j\in\mathbb{N}}} M_1\left(y_{ij}\right) \leq \\
\max\left\{1, k\delta^{-1} M_1(2) \lim_{\substack{y_{ij}>\delta, i, j\in\mathbb{N}}} M_1\left(y_{ij}\right) \tag{2.16}$$

therefore from (2.10) and (2.11) we have

$$I - \lim_{ij} M_1(\mathcal{Y}_{ij}) = 0$$

$$\implies I - \lim_{ij} M_1 M_2(\frac{|T(x_{ij})|}{\rho}) = 0.$$

This implies that $x = (x_{ij}) \in {}_{0}S_{0}^{I}(M_{1}M_{2})$. Hence $X(M_{2}) \subseteq X(M_{1}M_{2})$ for $X = {}_{0}S_{0}^{I}$ The other cases can be proved in similar way.

(b) Let $x = (x_{ij}) \in {}_2S_0^l(M_1) \cap {}_2S_0^l(M_2)$. Let $\epsilon > 0$ be given, then $\exists \rho > 0$. Such that,

$$I - \lim_{ij} M_1(x_{ij}) = 0$$
(2.17)

and

$$I - \lim_{ij} M_2(x_{ij}) = 0$$
(2.18)

therefore

$$\begin{split} I - \lim_{ij} M_1 + M_2(\frac{|T(x_{ij})|}{\rho}) &= I - \lim_{ij} M_1(\frac{|T(x_{ij})|}{\rho}) + I - \\ \lim_{ij} M_2(\frac{|Tx_{ij}|}{\rho}) \end{split}$$

from Eqs. (2.17) and (2.18)

$$\Rightarrow I - \lim_{ij} (M_1 + M_2) (\frac{|T(x_{ij})|}{\rho}) = 0.$$

We get

$$x = (x_{ij}) \in 2S_0^I(M_1 + M_2).$$

Hence we get

$$x = (x_{ij}) \in {}_2S_0^I(M_1 + M_2).$$

For ${}_{2}S^{I}$, ${}_{2}M^{I}_{s}(M)$ and ${}_{2}M^{I}_{S_{0}}$ the inclusion are similar.

Corollary: $X \subseteq X(M)$ For $X = {}_{2}S^{I}, {}_{2}S^{I}_{0}, {}_{2}M^{I}_{s}$ and ${}_{2}M^{I}_{S_{0}}$.

Theorem 2.3: For any Orlicz function M, the spaces ${}_{2}S_{0}^{I}(M)$ and ${}_{2}M_{S_{0}}^{I}(M)$ are solid and monotone.

Proof: Here we consider ${}_{2}S_{0}^{I}(M)$ and for ${}_{2}M_{S_{0}}^{I}(M)$ the proof shall be similar. Let $x = x_{ij} \in {}_{2}S_{0}^{I}(M)$ be an arbitrary element, $\Rightarrow \exists \rho > 0$ such that

$$I - \lim_{ij} M(\frac{|T(x_{ij})|}{\rho}) = 0.$$
(2.19)

Let (α_{ij}) be a sequence of scalars with $|\alpha_{ij}| \le 1$ for $i, j \in \mathbb{N}$.

Now, M is an Orlicz function and for $\epsilon > 0$, the results follows from the following inclusion

$$\begin{cases} (i,j) \in \mathbb{N} \times \mathbb{N} : M(\frac{|T(\alpha_{ij}x_{ij})|}{\rho}) \ge \epsilon \end{cases} \subseteq \begin{cases} (i,j) \in \mathbb{N} \times \\ \mathbb{N} : M(\frac{|T(x_{ij})|}{\rho}) \ge \epsilon . \end{cases}$$
(2.20)

This implies that,

$$I - \lim_{ij} M(\frac{|T(\alpha_{ij}x_{ij})|}{\rho}) = 0.$$
 (2.21)

Thus we have

$$\left(\alpha_{ij}x_{ij}\right)\in {}_2S_0^I(M).$$

Hence ${}_{2}S_{0}^{I}$ is solid. Therefore ${}_{2}S_{0}^{I}(M)$ is monotone. Since every solid sequence space is monotone. For ${}_{2}M_{S_{0}}^{I}(M)$ the proof shall be similar.

Theorem 2.4: For any Orlicz function M, the space ${}_{2}S^{I}(M)$ and ${}_{2}M^{I}_{s}(M)$ are neither solid nor monotone in general.

Proof: Here we give counter example for establishment of this result. Let $x = {}_{2}S^{I}$ and ${}_{2}M_{S}^{I}$. Let us consider $I = I_{\delta}$ and $M(x) = x^{2}$, for all $x = x_{ij} \in [0, \infty)$ and T an identity operator on \mathbb{R} . Consider, the K-step space $X_{K}(M)$ of X(M) defined as follows: Let $x = (x_{ij}) \in X(M)$ and $\mathcal{Y} = (\mathcal{Y}_{ij}) \in X_{K}(M)$ be such that

$$(\mathcal{Y}_{ij}) = \begin{cases} x_{ij} &, & \text{if } i+j \text{ even,} \\ 0 &, & \text{otherwise.} \end{cases}$$
(2.22)

Consider the sequence (x_{ij}) defined by $(x_{ij}) = 1$ for all $i, j \in \mathbb{N}$. Then $x = (x_{ij}) \in 2S^{I}(M)$ and $2M_{s}^{I}(M)$, but K-step space preimage does not belong to $2S^{I}(M)$ and $2M_{s}^{I}(M)$. Thus $2S^{I}(M)$ and $2M_{s}^{I}(M)$ are not monotone and hence they are not solid.

Theorem 2.5: For an Orlicz function M and an identity operator T on \mathbb{R} , the spaces ${}_{2}S_{0}^{I}(M)$ and ${}_{2}S^{I}(M)$ are sequence algebra.

Proof: Here we consider ${}_{2}S_{0}^{I}(M)$. Let $x = (x_{ij})$ and $\mathcal{Y} = (\mathcal{Y}_{ij}) \in {}_{2}S^{I}(M)$ be any two arbitrary elements. *There exists* $\rho_{1}, \rho_{2} > 0$ such that,

$$I - \lim_{ij} M(\frac{|T(x_{ij})|}{\rho_1}) = 0.$$
(2.23)

and

$$I - \lim_{ij} M(\frac{|T(y_{ij})|}{\rho_2}) = 0.$$
Let $\rho = \rho_1, \rho_2 > 0$ then
$$(2.24)$$

$$M(\frac{|T(x_{ij})T(y_{ij})|}{\rho}) = M(\frac{|T(x_{ij})|}{\rho_1}) M(\frac{|T(y_{ij})|}{\rho_2}) \Longrightarrow I - \lim_{ij} M\left(\frac{|T(x_{ij})T(y_{ij})|}{\rho}\right) = 0.$$

Therefore we have $(x_{ij}\mathcal{Y}_{ij}) \in {}_2S_0^I(M)$. Hence ${}_2S_0^I(M)$ is sequence algebra.

Theorem 2.6: Let M be an Orlicz function. Then

$${}_{2}S_{0}^{I}(M) \subsetneq {}_{2}S^{I}(M) \subsetneq {}_{2}S_{\infty}^{I}(M).$$

Proof: Let M be an Orlicz function. Then, we have to show that

$${}_{2}S_{0}^{I}(M) \subsetneq {}_{2}S^{I}(M) \subsetneq {}_{2}S_{\infty}^{I}(M).$$

Firstly, ${}_{2}S_{0}^{I}(M) \subsetneq {}_{2}S^{I}(M)$ is obvious. Now, let $x = (x_{ij}) \in {}_{2}S^{I}(M)$ be any arbitrary element $\Longrightarrow \exists \rho > 0$ such that $\Longrightarrow I - \lim_{ij} M\left(\frac{|T(x_{ij}) - L|}{\rho}\right) = 0$ for $L \in \mathbb{C}$. Now, $M\left(\frac{|T(x_{ij})|}{2\rho}\right) \le \frac{1}{2}M\left(\frac{|T(x_{ij}) - L|}{\rho}\right) + \frac{1}{2}M\left(\frac{|L|}{\rho}\right)$. Taking supremum over i, j to both sides, we have $x = (x_{ij}) \in {}_{2}S^{I}(M)$. Thus

 ${}_{2}S_{0}^{I}(M) \subsetneq {}_{2}S^{I}(M) \subsetneq {}_{2}S_{\infty}^{I}(M).$

Theorem 2.7: The set ${}_{2}M_{s}^{I}(M)$ is closed subspace of ${}_{2}S_{\infty}^{I}(M)$.

Proof: Let $x_{ij}^{(pq)}$ be a cauchy sequence in ${}_{2}M_{s}^{I}(M)$ such that $x_{ij}^{(pq)} \rightarrow x$. We show that $x = (x_{ij}) \in {}_{2}M_{s}^{I}(M)$.Since, $x_{ij}^{(pq)} \in {}_{2}M_{s}^{I}(M)$ the ther exists a_{pq} , and $\rho > 0$ such that

$$\{i, j \in \mathbb{N} \colon M \ (\frac{|T(x_{ij}^{(pq)})|}{\rho}) \ge \epsilon\} \in I.$$

We need to show that

1. a_{pq} , converges to a. 2. If $U = \left\{ i, j \in \mathbb{N} : M\left(\frac{|T(x_{ij})-a|}{\rho}\right) < \delta \right\}$, then $U^c \in I$.

Since $(x_{ij}^{(pq)})$ be a Cauchy sequence in ${}_{2}M_{s}^{I}(M)$ the for a given $\epsilon > 0$ there exists $k_{0} \in \mathbb{N}$ such that $\sup_{ij} M(\frac{|T(x_{ij}^{(pq)}) - T(x_{ij}^{(rs)})|}{\rho}) < \frac{\epsilon}{3}$, for all $p, q, r, s \ge k_{0}$. For a given $\epsilon > 0$, we have

$$B_{pqrs} = \{i, j \in \mathbb{N} : \left(\frac{|T(x_{ij}^{(pq)}) - T(x_{ij}^{(rs)})|}{\rho}\right) < \frac{\epsilon}{3}\},$$

$$B_{pq} = \{i, j \in \mathbb{N} : \left(\frac{|T(x_{ij}^{(pq)}) - a_{pq}|}{\rho}\right) < \frac{\epsilon}{3}\},$$

$$B_{rs} = \{i, j \in \mathbb{N} : \left(\frac{|T(x_{ij}^{(rs)}) - a_{rs}|}{\rho}\right) < \frac{\epsilon}{3}\}.$$

Then $B_{pqrs}^c, B_{pq}^c, B_{rs}^c \in I$. Let $B^c = B_{pqrs}^c \cap B_{pq}^c \cap B_{rs}^c$, where $B = \{i, j \in \mathbb{N}: M(\frac{|a_{pq}-a_{rs}|}{\rho}) < \epsilon\}$, then $B^c \in I$. We choose $k_0 \in B^c$, then for each $p, q, r, s \ge k_0$ we have

$$\begin{split} B &= \{i, j \in \mathbb{N} \colon M\left(\frac{|a_{pq} - a_{rs}|}{\rho}\right) < \epsilon\} \supseteq [\{i, j \in \mathbb{N} \colon M\left(\frac{|T(x_{ij}^{(pq)}) - a_{pq}|}{\rho}\right) < \frac{\epsilon}{3})\} \cap \{i, j \in \mathbb{N} \colon M\left(\frac{|T(x_{ij}^{(pq)}) - T(x_{ij}^{(rs)})|}{\rho} < \frac{\epsilon}{3})\} \cap \{i, j \in \mathbb{N} \colon M\left(\frac{|T(x_{ij}^{(rs)}) - a_{rs}|}{\rho}\right) < \frac{\epsilon}{3})\}] \end{split}$$

Then (a_{pq}) is a Cauchy sequence in \mathbb{C} . So, there exists a scalar $a \in \mathbb{C}$ such that

 $(a_{pq}) \rightarrow a \text{ as } p, q \rightarrow \infty.$

For the next step, let $0<\delta<1$ be given. Then, we show that if,

$$U = \{i, j \in \mathbb{N}: M(\frac{|T(x_{ij}) - a|}{\rho}) < \delta\}$$

then $U^c \in I$. Since $x_{ij}^{(pq)} \to x$, then there exists $p_0, q_0 \in \mathbb{N}$ such that,

$$P = \{i, j \in \mathbb{N} : M(\frac{\left|T\left(x_{ij}^{(p_0q_0)}\right) - T(x)\right|}{\rho}) < \frac{\delta}{3}\} \Longrightarrow P^C \in I.$$

The numbers p_0 , q_0 be so chosen such that we have

$$Q = \{i, j \in \mathbb{N} : M(\frac{|a_{p_0q_0} - a|}{\rho}) < \frac{\delta}{3}\}$$

such that $Q^C \in I$. Since $(x_{ij}^{(pq)}) \in {}_2M_s^I(M)$. We have

$$\{i, j \in \mathbb{N}: M(\frac{\left|T\left(x_{ij}^{(p_0q_0)}\right) - a_{p_0q_o}\right|}{\rho}) \ge \delta\}$$

then we have a subset S of N such that $S^C \in I$, where

$$S = \{i, j \in \mathbb{N}: M(\frac{\left|T\left(x_{ij}^{(p_0q_0)}\right) - a_{p_0q_0}\right|}{\rho}) < \frac{\delta}{3}\}$$

Let $U^C = P^C \cup Q^C \cup S^C$, where

$$U = \{i, j \in \mathbb{N} : M(\frac{|T(x) - a|}{\rho}) < \delta\}.$$

Therefore, for each $i, j \in U^C$, we have

$$\begin{split} &\{i,j \in \mathbb{N}: M(\frac{|T(x)-a|}{\rho}) < \delta \supseteq [\{i,j \in \mathbb{N}: M(\frac{|T(x_{ij}^{(p_0q_0)}) - T(x)|}{\rho}) < \\ &\frac{\delta}{3}\} \cap \{i,j \in \mathbb{N}: M\frac{|a_{p_0q_0}-a|}{\rho}) < \frac{\delta}{3}\} \cap \{i,j \in \\ &\mathbb{N}: M(\frac{|T(x_{ij}^{(p_0q_0)}) - a_{p_0q_0}|}{\rho}) < \frac{\delta}{3}\}. \end{split}$$

Hence the result ${}_{2}M_{s}^{I}(M) \subset {}_{2}S_{\infty}^{I}(M)$ follows.

3. Conclusion

In this paper we have studied a more general type of convergence for double sequences, that is I-Convergence as well as I-Cauchy in a more general setting i.e. compact operator is used to defined Iconvergence for double sequence space. These spaces and results provide new tools to deal with the convergence problems of double sequences occurring in many branches of science and engineering.

Acknowledgement

The authors would like to record their gratitude to the reviewer for his careful reading and making some useful corrections which improved the presentation of the paper.

References

- Başar F and Altay B (2003). On the space of sequences of pbounded variation and related matrix mappings. Ukrainian Mathematical Journal, 55(1): 136-147.
- Bhardwaj V and Singh N (2000). Some sequence spaces defined by Orlicz functions. Demonstratio Mathematica. Warsaw Technical University Institute of Mathematics, 33(3): 571-582.
- Buck RC (1953). Generalized asymptotic density. American Journal of Mathematics, 75(2): 335-346.
- Et M (2001). On some new Orlicz spaces. Journal of Analysis, 9: 21-28.
- Fast H (1951). Sur la convergence statistique. In Colloquium Mathematicae, 2(3-4): 241-244.
- Hazarika B and Esi A (2013). Some I-convergent generalized difference lacunary double sequence spaces defined by Orlicz function. Acta Scientiarum. Technology 35(3): 527–537.
- Khan VA and Ebadullah K (2011). On some I-Convergent sequence spaces defined by a modulus function. Theory and Applications of Mathematics and Computer Science, 1(2): 22-30.
- Khan VA and Ebadullah K (2013). Zweier I-convergent sequence spaces defined by Orlicz function. Analysis, 33(3): 251-261.
- Khan VA, Ebadullah K, and Suantai S (2012). On a new Iconvergent sequence space. Analysis International Mathematical Journal of Analysis and Its Applications, 32(3): 199-208.
- Khan VA, Shafiq M, Rababah RKA, and Esi A (2016). On some Iconvergent sequence spaces defined by a compact operator. Annals of the University of Craiova-Mathematics and Computer Science Series, 43(2): 141-150.
- Kostyrko P, Mačcaj M, Sčala't T, and Silezaik M (2005). Iconvergence and extremal I-limits points. Mathematica Slovaca, 55(4): 443-464.

- Kostyrko P, Wilczyński W, and Šalát T (2000). I-convergence. Real Analysis Exchange, 26(2): 669-686.
- Lindenstrauss J and Tzafriri L (1971). On Orlicz sequence spaces. Israel Journal of Mathematics, 10(3): 379-390.
- Maddox IJ (1970). Elements of functional analysis. Cambridge at the University Press, Cambridge, UK.
- Parashar SD and Choudhary B (1994). Sequence spaces defined by Orlicz functions. Indian Journal of Pure and Applied Mathematics, 25: 419-419.
- Šalát T (1980). On statistically convergent sequences of real numbers. Mathematica Slovaca, 30(2): 139-150.
- Šalát T, Tripathy BC, and Ziman M (2004). On some properties of I-convergence. Italian Journal of Pure and Applied Mathematics, 28(2): 274-286.
- Šalát T, Tripathy BC, and Ziman M (2005). On I-convergence field. Italian Journal of Pure and Applied Mathematics, 17(5): 1-8
- Schoenberg IJ (1959). The integrability of certain functions and related summability methods. The American Mathematical Monthly, 66(5): 361-375.
- Sengonul M (2007). On the Zweier sequence space. Demonstratio Mathematica. Warsaw Technical University Institute of Mathematics, 40(1): 181-196.
- Tripathy BC (2004). On generalized difference paranormed statistically convergent sequences. Indian Journal of Pure and Applied Mathematics, 35(5): 655-664.
- Tripathy BC and Hazarika B (2009). Paranorm I-convergent sequence spaces. Mathematica Slovaca, 59(4): 485-494.
- Tripathy BC and Hazarika B (2011). Some I-convergent sequence spaces defined by Orlicz functions. Acta Mathematicae Applicatae Sinica, English Series, 27(1): 149-154.